A Tale of Two Planning Projects: The Frontiers of Science and Robotics

SCUP 2022 Annual Conference

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Introductions, Agenda, and Objectives

Introductions



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Agenda & Outcomes

Today's Agenda

5 min Introductions & Objectives

10 min CMU's Challenges & Goals

5 min Poll and Discussion

10 min Visioning and Programming

10 min Site Strategy and Design

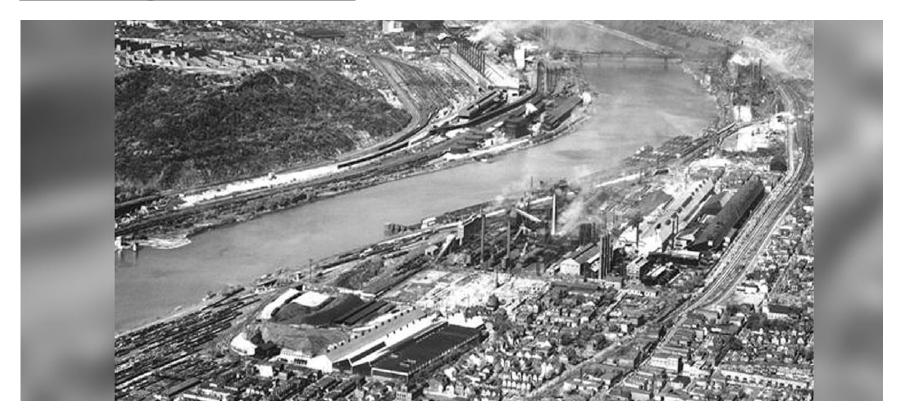
10 min Lessons Learned & Q&A

Learning Outcomes

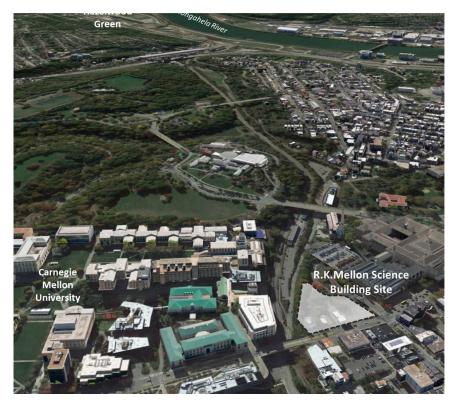
- Free up space on your main campus by exploring planning on the frontiers of your campus
- 2. Evaluate issues in interdisciplinary planning at your institution
- 3. Create a flexible programming model to forecast needs for the future
- 4. Effectively engage faculty in your planning effort

CMU's Challenges and Goals

Pittsburgh of the Past



A Tale of Two Projects





A Tale of Two Projects

Interdisciplinary Science Center

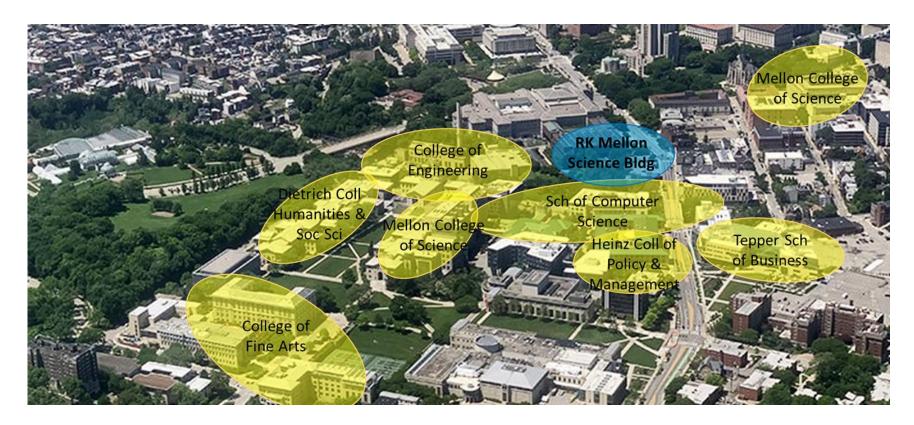
340,000 GSF Complex at edge of campus adjacent to Museum and public library creating research hubs and housing contemporary art institute/gallery.

(w/ RFD Lab Planners)

Robotics Innovation Center

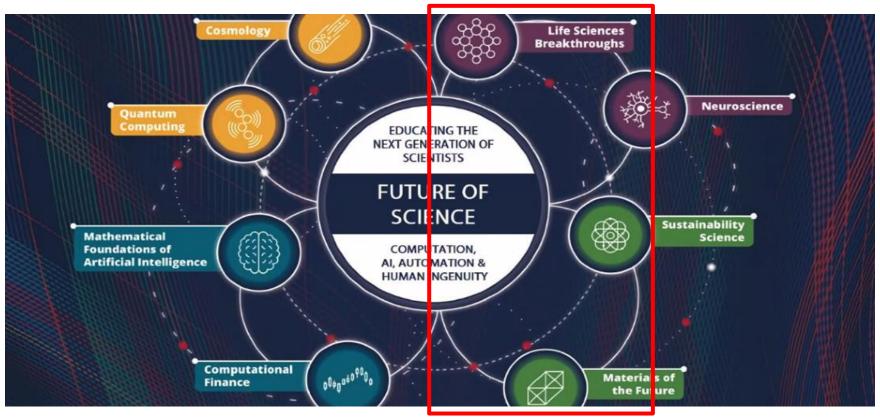
150,000 GSF Off-campus center for robotics bringing together CMU's School of Computer Science, College of Engineering, and Corporate/Government partners.

Interdisciplinary Science Need



Interdisciplinary Science Need

Project Focus



Interdisciplinary Science Vision



Interdisciplinary Science Principles

Embrace Hubs Across Disciplines Reduce
Dependence on
Mellon Institute
Building

Expand
Collaboration
Space

Adopt a Core Facilities Sharing Model

Plan to
Contemporary Lab
Standards

Promote the Offsite Cloud Lab Facility

Support
Teaching and
Learning

Avoid Office Duplication

Interdisciplinary Science Goals

Mellon College of Science Goals	School of Com Go
Optimize for collaboration, discovery, and creativity	Focus on researce fostering collaborand beyond SCS
Invite informal connections and community building	Improve the stud

Enable hubs to co-locate and evolve

Share core labs and support facilities

Leverage the off-site cloud lab facility

nputer Science oals

ch spaces, oration within

Improve the student experience by expanding

shared study space and classroom spaces

Free up space in other SCS facilities for expansion

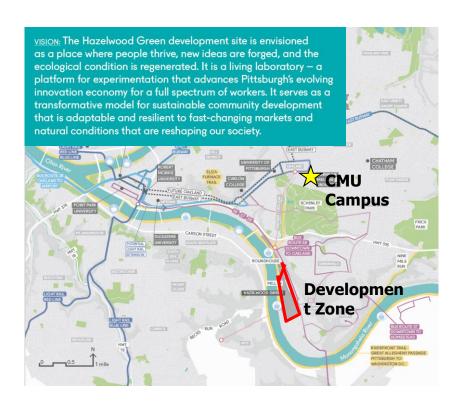
College of Fine Arts Goals

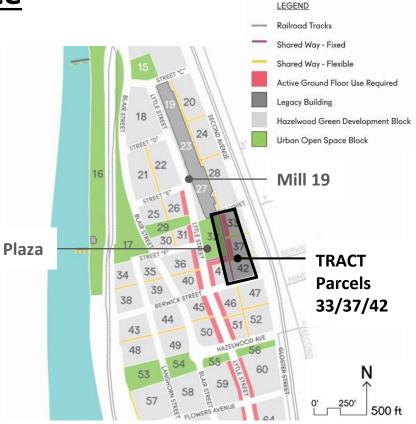
Raise the profile of the arts at CMU

Welcoming the public with a prominent ground floor location adjacent to the Carnegie Museums

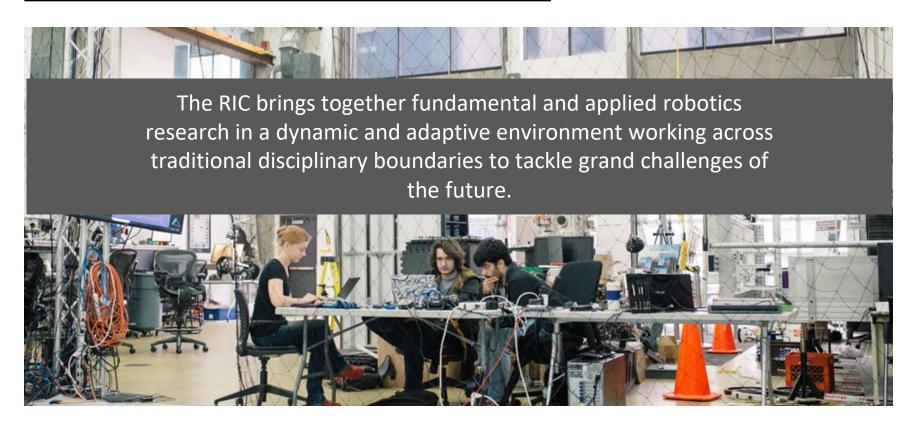
Support expanded gallery operations with ample staff space, workshop space and art handling space

Robotics Innovation Center Site





Robotics Innovation Center Vision



Robotics Innovation Center Goals

<u>Integrated</u>

Enable researchers to conduct fluid, integrated, translational research and seamlessly field test robots and autonomous systems across indoor, outdoor and virtual environments

Destination

Create a world-class destination for robotics and autonomous systems to attract talent, inspire future generations, build & strengthen partnerships and showcase innovation

Incubator

Provide incubator space and support to pre-seed startups to strengthen and accommodate partnerships in the industry of robotics and autonomous systems

Community

Engage and enhance the local community and create a placemaking destination at Hazelwood Green

Robotics Innovation Center Principles



Design spaces to flex for multiple uses throughout the day or for rotating project teams



Create opportunities for meaningful connection with the robotics community, local neighbors, and industry partners



Adaptability

Install robust infrastructure to enable long-term changes to spaces



Get people to come here, and help build an identity for Hazelwood Green



Share our research process and outcomes by curating visibility for the public and partners



Welcome and accommodate users of all levels of ability and experience to engage and contribute

Common Themes: Context, Vision, and Goals

Building upon past studies and internal work

Creating consensus and shared vision

Translating donor agreements into reality

Complementing, not duplicating existing facilities

Enabling expansion in existing facilities

Planning for Uncertainty

Poll and Discussion

What are your 3 biggest challenges planning next gen science and engineering facilities?

Changing to more efficient workspace standards Moving to a more distributed model (I.e., depts divided) Shifting to more shared equipment and space Providing shell space for expansion Welcoming corporate and government partners Building consensus across disciplines and departments Aligning vision, site, program, and budget Keeping institutional memory across phases of work Aligning donor and institutional priorities Planning despite uncertainty from Covid



Visioning and Programming

Programming Approach



Core Users
Mix of users
(researchers/
staff/students)



Populations
Team size by
user type



Space Allocation
Area needed by
user and team
(workspace
/support)



Shared
Facilities
(computing support, storage)



Public Space (lobby, study, retail)



Space Program (57,000 NASF)

Interdisciplinary Science Groups

Biological Sciences
Department

Chemistry Department

Neuroscience Institute Computational Biology Department

Language Technology Institute Machine Learning
Department

Contemporary
Art
Institute

Science Dean's Office

Interdisciplinary Science Populations

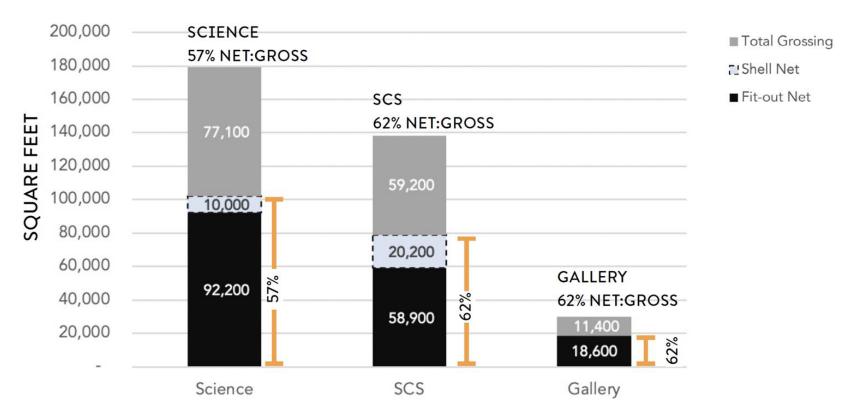
	Science	SCS*	Gallery	Total
Faculty Researchers	44	61	-	105
Teaching Faculty	7	7	=-	14
Research Team Members**	232	311	-	543
Undergrad Researchers	41	-	π.	41
Visiting Researchers	10	12	=.	22
Students (non-research)	288	302	30	620
Est. Daily Gallery Visitors	i.e.	_	165	165
Total Staff	42	53	10	105
Total Occupants	664	746	205	1,615

^{**} Includes PhD, Post Docs, Research Techs, and Research Masters Students

Interdisciplinary Science Program

	Science	SCS*	Gallery	Total
Study Space	2,900	5,700	900	9,500
Classrooms	2,900	3,300	Ð	6,200
Laboratories	44,300	2,500	-	46,800
Workspace	30,300	43,600	900	74,800
General Use	6,900	1,800	16,500	25,200
Building Support	5,000	1,800	600	7,400
TOTAL FIT-OUT NASF	92,300	58,700	18,900	169,900
Shell Space	10,000	21,700	-	31,700
TOTAL LONG-TERM NASF	102,300	80,400	18,900	201,600

Interdisciplinary Science Program



Interdisciplinary Science Public/Learning Spaces



Lobby and Cafe



Bio Teaching Labs



Classrooms



Galleries



Wet Research Labs



Computational Labs



Core Labs



Offices

Robotics Populations





CMU students

75 total students

Masters and

or research.

undergraduate

students who are

involved in robotics









CMU Research Teams

85 total researchers

Faculty and their teams of PhDs, post docs, and other full-time research specialists.

Use Case:

Use Case:

Conducting
fundamental to
applied research
across disciplines and
with partners

Use Case:
Contributing to CMU
research teams and
studying for courses

CMU Staff

12 total staff

School support staff, specialist staff, and building managers.

Use Case:

Managing the facilities and supporting day to day research and programming **Incubator Teams**

12 total entrepreneurs

CMU students and faculty and staff building start-ups and spin-offs

Use Case:

Developing early-phase start ups into functioning enterprises while leveraging CMU labs and expertise Government and industry partners

transient/varies

Policy makers and industry partners supporting and advancing CMU research

Use Case:

Visiting the facility to see outcomes of funding and explore next steps

General Public and Neighbors

transient/varies

Neighbors and visitors curious about robotics

Use Case:

Visiting exhibits and attending events and trainings

Robotics Program

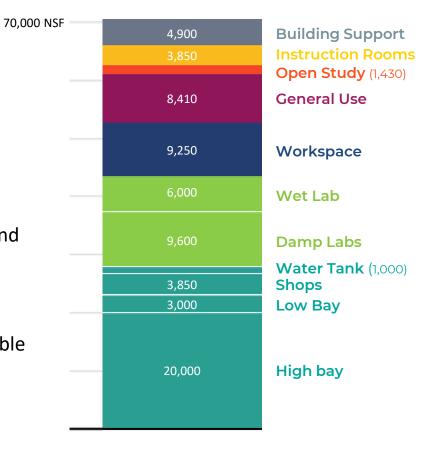
The new facility provides ~70,000 NASF of space for research, experimentation, working, and public engagement (not incl. 50,000 GSF shell space)

17% of the facility for lobby, café, visitor center, childcare, and instruction rooms

62% of the facility for high and low bays, shops, and wet and damp labs

15% of the facility for workspace and open study

7% of the facility for building support spaces; double the standard allocation for a building of this scale



Robotics Instruction, Work, and Study Spaces



Lobby



Cafe



Visitors Center



Childcare



Instructional Space



High Bay



Low Bay



Damp Labs



Workspace



Study Spaces

Common Themes: Space Programming & Planning

Shifts to smaller, more shared space standards

Planning for change in science and engineering

Effective digital stakeholder engagement

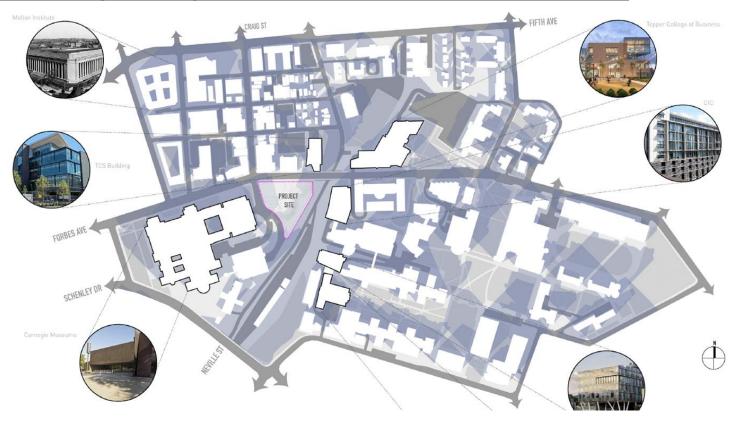
Moving target for area, net-to-gross, and shell space

Providing just enough detail to make decisions

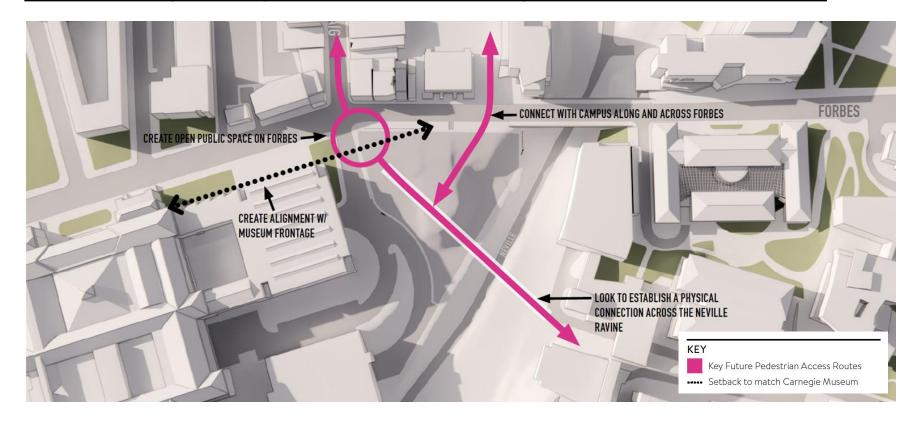
Delightful to interview faculty on their work and how it's changing

Site Strategy and Design

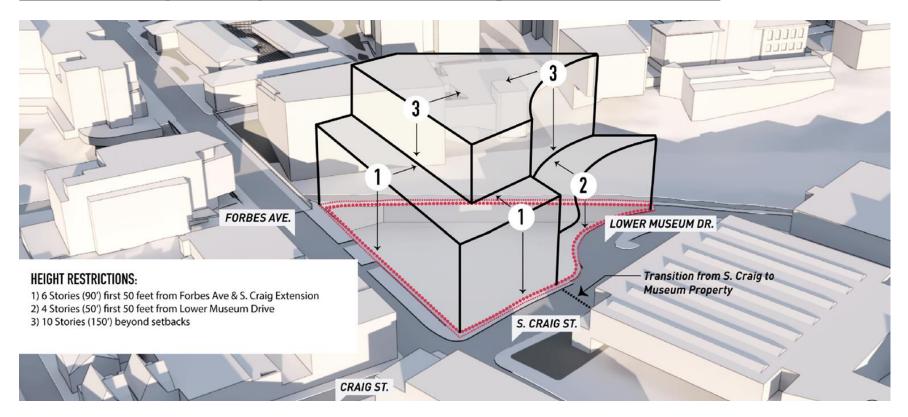
Interdisciplinary Science Context and Views



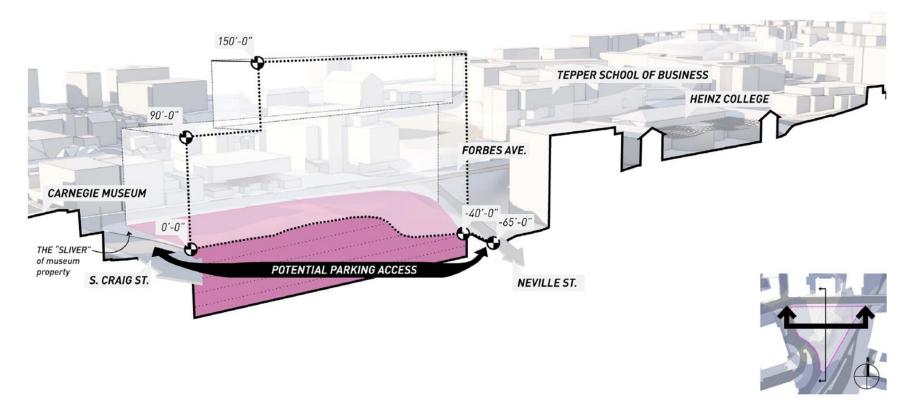
Interdisciplinary Science Masterplan Site Guidelines



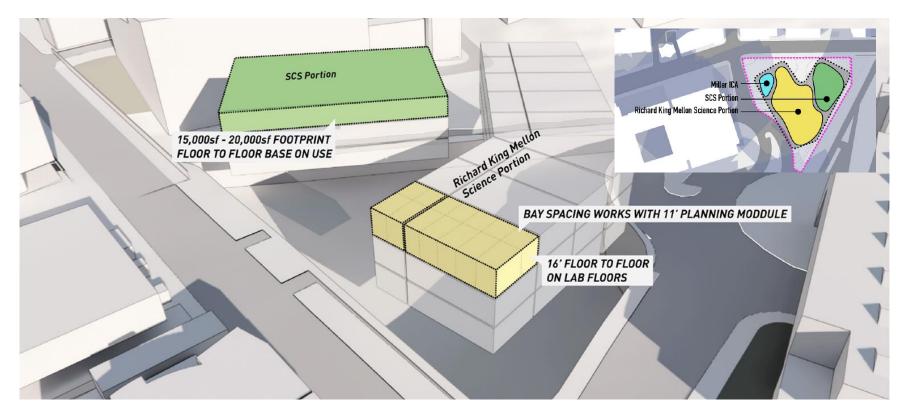
Interdisciplinary Science Zoning and Setbacks



Interdisciplinary Science Site Section

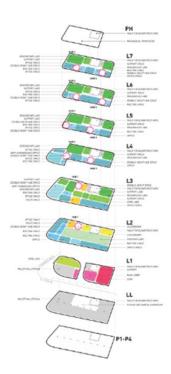


Interdisciplinary Site Strategy



Interdisciplinary Science Massing Concept

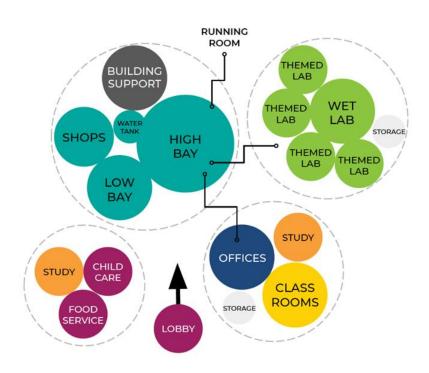




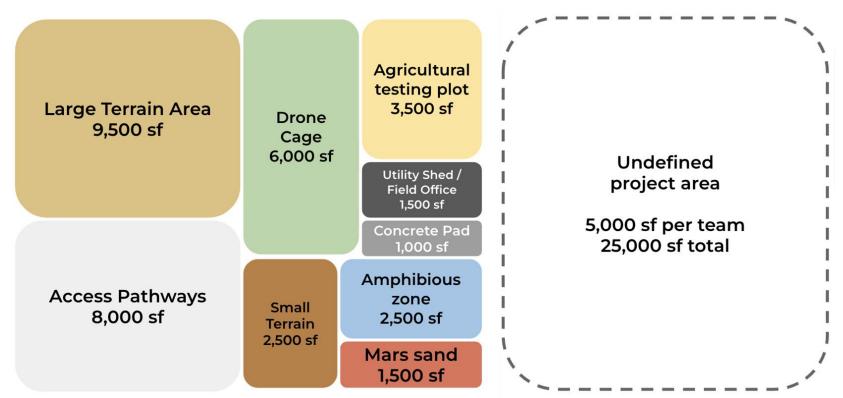
Robotics Adjacencies

Principles

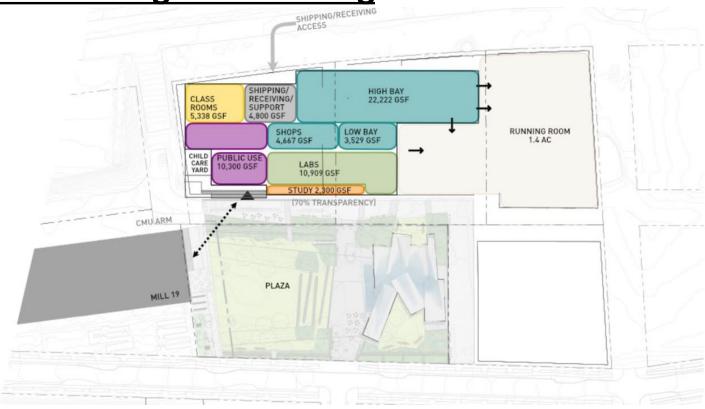
- Facilitate visibility and access to <u>community spaces</u> from the <u>entry</u> and to each other (classrooms, eatery, lobby, etc.)
- Showcase research activities safely for <u>visitors</u> with windows from meeting rooms into the <u>high bay</u>
- Locate <u>shops</u> and makerspaces near <u>classrooms</u> to support K-12 and workforce education programs, if possible.
- Distribute <u>study</u> space for flexibility and seating variety
- Locate restrooms, kitchenettes, and wellness rooms near the research work areas
- Create direct access from <u>high bay</u> to the <u>running room</u>
- Locate <u>low bay</u> adjacent to <u>high bay</u>, with direct access the <u>running</u> <u>room</u> if possible
- Create easy access from <u>shops</u> to the <u>labs</u> and <u>bay</u> spaces
- Locate <u>storage</u>/staging areas near <u>bays</u> and project teams
- Position <u>themed labs</u> adjacent to <u>each other</u> and the <u>bays</u>, and split across vertical levels if ramps / freight elevators can transport large robots



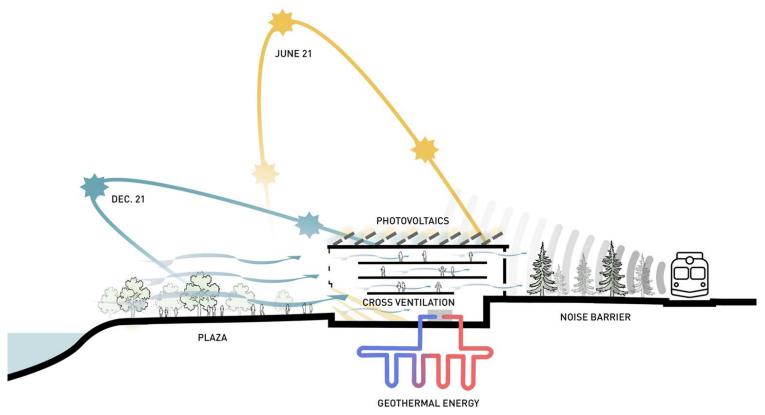
Robotics Outdoor Space



Robotics Blocking and Stacking



Robotics Environmental Opportunities



Robotics: Exploring Options

- Prominent public location adjacent to Plaza and visible to community of Hazelwood for public access
- Adjacent to ARM and CMU at Mill 19
- Two stories for immediate buildout;
 opportunity to expand into third floor
- Parcel 41 available for future development or growth of RIC
- Running room of about 1.4 acres
- Will require 70% transparency requirement along plaza frontage and vacating two shared ways



High Bay on Second Ave



Common Themes: Site Strategy and Design

Maximizing buildable area within site constraints

Access to daylight and views

Identify locations for functional operations: loading, parking, etc.

Creating intuitive locations for high prioriority functions

Providing just enough detail to make decisions

Capitalize on connections to adjacent buildings and the greater campus

Lessons Learned and Q&A

Lessons Learned and Q&A

Virtual engagement enables more participation and more equitable process

Encourage interdisciplinarity through shared labs and "no names on doors"

It takes patience, finesse, and the right info to align views

Address conflicting views as they arise; don't table it for later when stakes are higher

Need to educate leadership on the value of spending time and money pre-planning

Need a nimble process at the fuzzy front-end, lots of scenarios and options!

Thank you!

Carnegie Mellon University





Planning at the Frontiers of Science and Robotics

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